

EC centrifugal module - RadiPac

backward-curved, single-intake

with support bracket

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Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	K3G560-PB31-61	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min ⁻¹	1700
Power consumption	W	4400
Current draw	A	6.6
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment

Subject to change

Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	69.9	58.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		73.8	62
05 Variable speed drive		Yes	

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

09 Power consumption P_{ed}	kW	4.25
09 Air flow q_v	m ³ /h	9825
09 Pressure increase p_{fs}	Pa	1049
10 Speed (rpm) n	min ⁻¹	1700
11 Specific ratio*		1.01

* Specific ratio = $1 + p_{fs} / 100\,000\text{ Pa}$

LU-183216



Technical description

Weight	51.8 kg
Size	560 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Ambient temperature note	Occasional start-up at temperatures between -40°C and -25°C is permitted. For continuous operation at ambient temperatures below -25°C (such as refrigeration applications), use must be made of a fan design with special low-temperature bearings.
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See product drawing
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Operation and alarm display with LED - External 15-50 VDC input (parameterization) - Alarm relay - Integrated PI controller - Configurable inputs/outputs (I/O) - MODBUS V6.0 - Motor current limitation - RFID - ISO 15693 compatible - RS-485 MODBUS-RTU - Soft start - Voltage output 3.3-24 VDC, Pmax = 800 mW - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used equipment with a total rated power greater than 1 kW
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE

K3G560-PB31-61

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Approval

UL 1004-7 + 60730-1; CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC

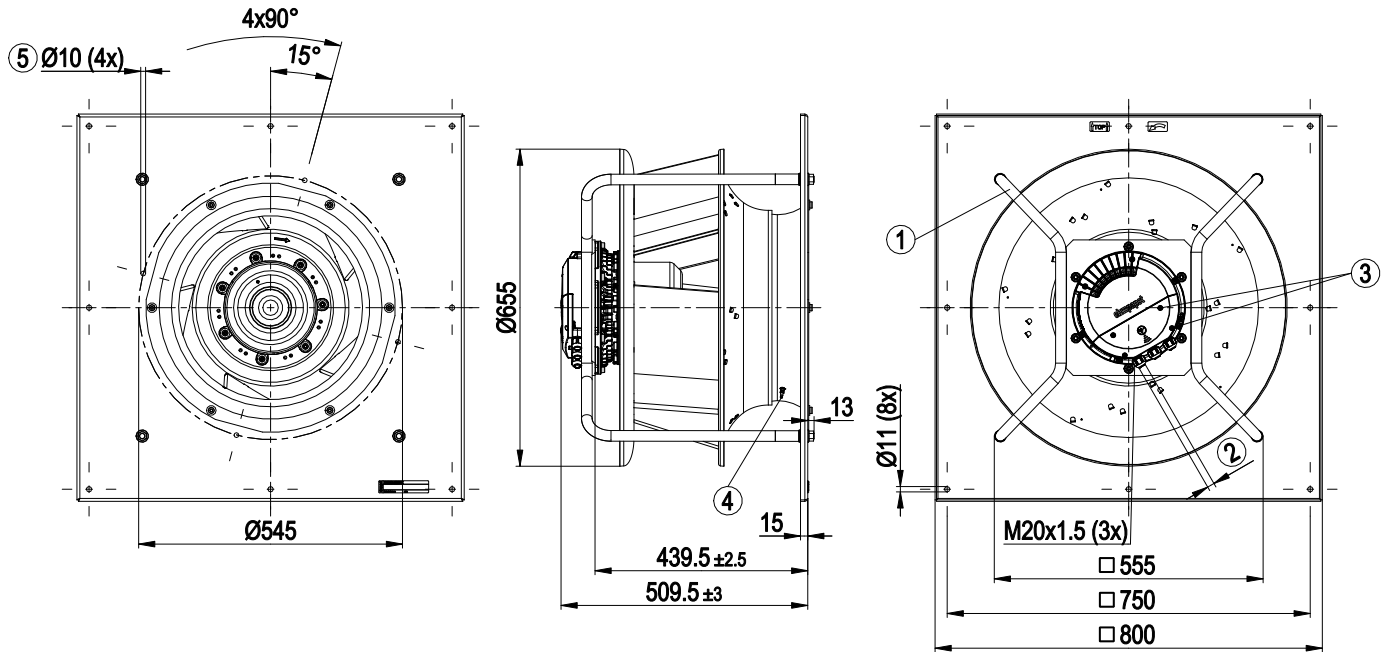


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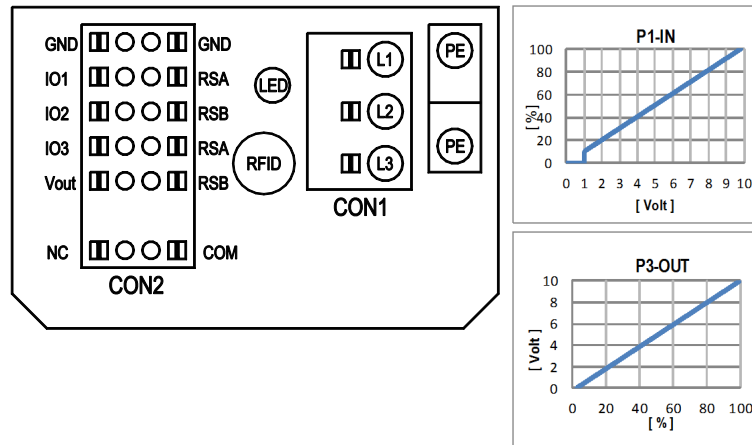
with support bracket

Product drawing



1	Installed position: shaft horizontal (install support struts only vertically as illustrated) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 2 ± 0.3 Nm
3	Tightening torque 1.5 ± 0.2 Nm
4	Inlet ring with pressure tap (k-factor: 348)
5	Mounting holes for FlowGrid

Connection diagram



No.	Conn.	Designation	Function/assignment
	CON1	L1, L2, L3	Power supply, phase, see nameplate for voltage range
	PE	PE	Protective earth
	CON2	RSA	RS485 interface for MODBUS, RSA; SELV
	CON2	RSB	RS485 interface for MODBUS, RSB; SELV
	CON2	GND	Reference ground for control interface, SELV
	CON2	IO1	Function parameterizable (see "Optional interface functions" table) Factory setting: Digital input - high active, function: Disable input, SELV - inactive: Pin open or applied voltage < 1.5 VDC - active: applied voltage 3.5-50 VDC Reset function: Triggering of error reset on change of state from "enabled" to "disabled"
	CON2	IO2	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog input 0-10 V / PWM, Ri=100 kΩ, function: Set value Characteristic curve parameterizable (see input characteristic curve P1-IN), SELV
	CON2	IO3	Function parameterizable (see "Optional interface functions" table) Factory setting: Analog output 0-10 V, max. 5 mA, function: Fan modulation level Characteristic curve parameterizable (see output characteristic curve P3-OUT), SELV
	CON2	Vout	Voltage output 3.3-24 VDC ±5%, Pmax=800 mW, voltage parameterizable Factory setting: 10 VDC short-circuit-proof, supply for external devices, SELV alternatively: 15-50 VDC input for parameterization via MODBUS without line voltage
	CON2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA, reinforced insulation on supply side and on control interface side
	CON2	NC	Status relay, floating status contact, break for failure
		LED	green: status = good, ready for operation orange: status = warning red: status = failure
		P1-IN	Input characteristic curve
		P3-OUT	Output characteristic curve

Terminal/plug assignment

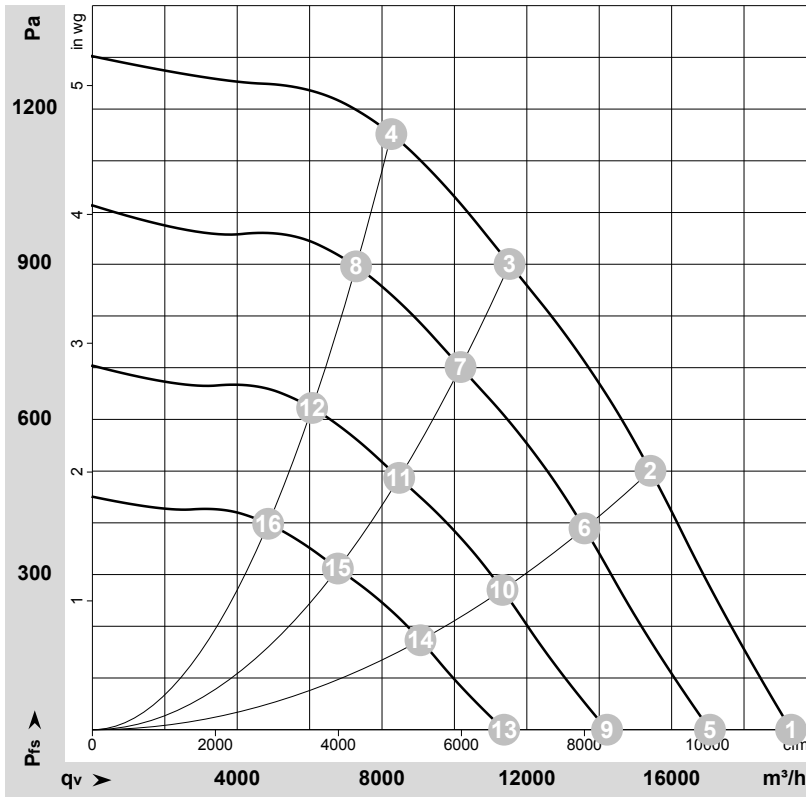
configurable option																													
For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.0																													
CON2	configurable IO mode	electrical specification	configurable IO functions: normal / inverse	MODBUS Register for IO mode configuration	INPUT										OUTPUT														
					Din1 (active high): digital input	not active: pin open or applied voltage < 1,5VDC active: applied voltage 3.5-50VDC, SELV	D158 [0]	○	switch: fan enable / disable	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing				
	IO1	Ain1 0-10V/PWM: analog input	RI=100K, characteristic curve parameterizable, f _{PWM} =1k..10KHz, SELV	D158 [2]	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing		
		Tach out (open collector output)	U _{max} =50VDC, I _{max} =20mA, SELV	D158 [5]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing
		Diagnostics out (open collector output)	U _{max} =50VDC, I _{max} =20mA, SELV	D158 [6]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing
		IO2	Din2 (active high): digital input	not active: pin open or applied voltage < 1,5VDC active: applied voltage 3.5-50VDC, SELV	D159 [0]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]
	Ain2 0-10V/PWM: analog input		RI=100K, characteristic curve parameterizable, f _{PWM} =1k..10KHz, SELV	D159 [2]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing
	Ain2 4-20mA: analog input		RI=125R, characteristic curve parameterizable, SELV	D159 [3]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing
	Din3 (active high): digital input		not active: pin open or applied voltage < 1,5VDC active: applied voltage 3.5-50VDC, SELV	D15A [0]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing
	IO3	Din3 (active low): digital input	not active: pin open or applied voltage < 1,5VDC active: applied voltage 3.5-50VDC, SELV	D15A [1]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing
PWMIn3: digital input		not active: pin open or applied voltage < 1,5VDC, SELV active: applied voltage 3.5-50VDC, SELV	D15A [7]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing	
Aout3 0-10V: analog output		function parameterizable, max. 5mA, max output frequency 300Hz, SELV	D15A [4]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing	
Tacho out (pulses), analog output		0-10V/max. 5mA, max output frequency 300Hz, SELV	D15A [5]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing	
RSA RSB	Diagnostics out (pulses)	0-10V/max. 5mA, max output frequency 300Hz, SELV	D15A [6]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing	
	RS485 bus connection,	MODBUS RTU, specification V6.0, SELV		○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing	
Yout	voltage output	voltage parameterizable 3.3...24VDC +/- 5.5%, P _{max} =800mW, short-circuit-proof, supply for external devices, SELV	D16E [...]	○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing	
	alternatively: input auxiliary power supply for parameterization via RS485/MODBUS RTU without line voltage	15...50VDC		○	switch: parameter set: #1 / #2	○	switch: control function: heating (pos.), cooling (neg.)	○	switch: direction of rotation: cw / ccw	D148 [...]	D16C [...]	D16A [...]	(selected directly via IO mode)	signal: tach out	(selected directly via IO mode)	signal: diagnostics out	D130 [0]	signal: fan modulation level %	D130 [1]	signal: actual speed	D130 [2]	signal: system modulation level %	D130 [3]	signal: remote control output 0-10V	D00C [1]	pulse input for auto-addressing	D130 [4]	pulse output for auto-addressing	

◦ configurable option

For further information and additional functions see EC Control Software, Fan-Set-App, or MODBUS Parameter Specification V6.0



Curves: Air performance 50 Hz



$$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$$

Measurement: LU-183216-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P _{ed}	I	LpA _{in}	LwA _{in}	LwA _{out}	q _v	P _{fs}	q _v	P _{fs}
	V	Hz	min ⁻¹	W	A	dB(A)	dB(A)	dB(A)	m ³ /h	Pa	cfm	in. wg
1	400	50	1700	2717	4.17	94	102	100	19300	0	11360	0.00
2	400	50	1700	3739	5.69	85	91	91	15415	500	9075	2.01
3	400	50	1700	4400	6.60	75	83	87	11525	900	6785	3.61
4	400	50	1700	4238	6.47	79	87	89	8255	1150	4860	4.62
5	400	50	1500	1876	2.88	91	99	97	17060	0	10040	0.00
6	400	50	1500	2563	3.90	82	88	88	13595	393	8000	1.58
7	400	50	1500	3012	4.57	72	80	84	10170	701	5985	2.81
8	400	50	1500	2908	4.44	76	83	86	7285	899	4285	3.61
9	400	50	1250	1086	1.67	86	95	93	14215	0	8365	0.00
10	400	50	1250	1483	2.26	77	84	83	11330	273	6665	1.10
11	400	50	1250	1743	2.65	68	75	79	8475	487	4990	1.96
12	400	50	1250	1683	2.57	71	79	82	6070	624	3570	2.51
13	400	50	1000	556	0.85	81	89	87	11375	0	6695	0.00
14	400	50	1000	759	1.16	72	78	78	9060	175	5335	0.70
15	400	50	1000	892	1.35	62	69	73	6780	312	3990	1.25
16	400	50	1000	862	1.32	66	73	76	4855	400	2860	1.61

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_v = Air flow · P_{fs} = Pressure increase

