

# MTi-610

- **Small, IP 51 rated IMU**
- **Factory calibrated inertial data**
- **Full GUI and SDK available**

The MTi-610 is a Inertial Measurement Unit with a small form-factor design for deep integration into your application. Building on the proven MTi 600-series technology it enables a robust and easy to use motion tracking. It is designed for easy integration and seamless interfacing with other equipment.

The MTi-610 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms.



## IMU performance

|                             |            |
|-----------------------------|------------|
| Accelerometer               | Calibrated |
| Gyroscope                   | Calibrated |
| Strapdown Integration (SDI) | Yes        |

## Gyroscope

|                         |               |
|-------------------------|---------------|
| Standard full range     | 2000 deg/s    |
| In-run bias stability   | 8 deg/h       |
| Bandwidth (-3dB)        | 520 Hz        |
| Noise Density           | 0.007 °/s/√Hz |
| g-sensitivity (calibr.) | 0.001 °/s/g   |

## Accelerometer

|                       |                   |
|-----------------------|-------------------|
| Standard full range   | 10 g              |
| In-run bias stability | 10 (x,y) 15(z) µg |
| Bandwidth (-3dB)      | 500 Hz            |
| Noise Density         | 60 µg/√Hz         |

## Magnetometer

|                     |         |
|---------------------|---------|
| Standard full range | +/- 8 G |
| Total RMS noise     | 1 mG    |
| Non-linearity       | 0.2%    |
| Resolution          | 0.25 mG |

## GNSS Receiver

|                 |     |
|-----------------|-----|
| Brand           | n/a |
| Model           | n/a |
| RTCM input port | n/a |

## Barometer

|                     |                  |
|---------------------|------------------|
| Standard full range | 300-1250 hPa     |
| Total RMS noise     | 1.2 Pa           |
| Relative accuracy   | +/- 8 Pa (~0.5m) |

## Mechanical

|                       |                                             |
|-----------------------|---------------------------------------------|
| IP-rating             | IP51                                        |
| Operating Temperature | -40 to 85 °C                                |
| Casing material       | PC-ABS                                      |
| Mounting orientation  | No restriction, full 360° in all axes       |
| Dimensions            | 28x31.50x13 mm                              |
| Connector             | Main: Phoenix Contact 16 pin, 1.27 mm pitch |
| Weight                | 8.9 g                                       |

## Electrical

|                         |            |
|-------------------------|------------|
| Input voltage           | 4.5 to 24V |
| Power consumption (typ) | <1 W       |

## Interfaces / IO

|                    |                            |
|--------------------|----------------------------|
| Interfaces         | UART, CAN, RS232           |
| Sync Options       | SyncIn, SyncOut, ClockSync |
| Protocols          | Xbus, ASCII (NMEA) or CAN  |
| Clock drift        | 10 ppm (or external)       |
| Output Frequency   | 2 kHz, 400 Hz SDI          |
| Built-in-self test | Yes                        |

## Software Suite

|                     |                                                             |
|---------------------|-------------------------------------------------------------|
| GUI (Windows/Linux) | MT Manager Firmware updater, Magnetic Field Mapper          |
| SDK (Example code)  | C++, C#, python, Matlab, Nucleo, public source code         |
| Drivers             | LabVIEW, ROS, GO                                            |
| Support             | BASE by XSENS: online manuals, community and knowledge base |

- White label and OEM integration options available
- 3D models available on request
- Available online via Digi-Key, Mouser, Farnell and local distributors